

Overview of the basic Matlab functions

```

help [anything]                                %help for command/function 'anything'
A=3;                                         %matrix A consists of a single element with the value 3
A1=3+i*6;                                    %A1 is complex: Re{A1}=3, Im{A1}=6
A2=3*exp (j*45)                           %A2 is complex: magnitude=3, angle=45°
B=[1,2,3];                                     %B is a vector with 3 elements
C=[1,2,3;4,5,6];                            %C is a matrix with 2 rows and 3 columns
D=[];                                         %D is an empty matrix
x=inf;                                        %x is equal to infinity
x=nan;                                         %Value of x is undefined e.g. result of a division by 0
x=B(i);                                       %x has the value of the i-th element of the vector B
x=C(i,j);                                     %x has the value of the element in the i-th row and the j-th column of the matrix C
x=C(:,i);                                      %x is a vector and contains all values of the i-th row of C
x=C(:,k:l);                                    %x is a vector and contains all values of the i-th row that belong to the columns k to l
E=zeros(M,N);                                 %(M x N) zero matrix (M x M if no N specified), i.e. E(i,j)=0
E=ones(M,N);                                  %(M x N) matrix (M x M if no N given) with E(i,j)=1
E=[1:1:10];                                    %equivalent E=[1,2,3,4,5,6,7,8,9,10] (general E=[a:n:b] and a, b, n real numbers) %
[n,m]=size(C);                               %dimensions of matrix C
l=length(B);                                   %length of the vector/matrix B
3*B;                                         %all values of B are multiplied by 3
B'                                            %matrix/vector transpose
C=B1 .* B2;                                 %C(i,j) = B1(i,j)*B2(i,j) (necessary condition: dim(B1) = dim(B2))
x^3;                                         %X3
C=B.^3;                                       %C(i,j) = [B(i,j)]^3
B^-1;                                         %inverse of matrix B
conj(U);                                      %conjugate complex matrix to U
abs(z);                                       %absolute value and complex magnitude of the complex number z
angle(z);                                     %angle of the complex number z
real(z);                                       %real part of the complex number z
imag(z);                                      %imaginary part of the complex number z
mod(x,y);                                     %modulo(x,y) (in C++ syntax: x%y) - remainder after division
x=sum(B);                                     %sum of array elements

x=find(B>1);                                %x is a vector which contains all indices of those elements
                                                %of B which satisfy the condition bi>1 (for matrices also
                                                %notation C(z,s)=find(C>1) possible)

[R1,R2,...] =BelFun(Matrix,Vektor,Variable,const...); %function call of a function BelFun(...); the elements R1, R2
                                                %etc. are assigned the return of the function.

function[R1,R2...]=BelFun(Matrix,Vektor,Variable,const) %function declaration

if (x~=1)...                                % if-else statement (condition true if x is not equal to 1).
elseif(x>=1|x==4&h<4)                      %condition true if (x >=1) or (x=4 and h<4)
... else ... end;                           %termination/termination of the statement
for (i = 1:n)...end;                         %counting loop: i is incremented by 1 in each iteration, i runs here from 1:n
while(...)...end;                           %while loop.
diag(ones(n,1));                             %creates a unit matrix with dim n x n
sort(C);                                       %sorts elements of C
isempty(C);                                     %true if C contains no elements
sin(A),cos(a) ...                           %sin, cos... of a number or any element of the matrix

```

MATLAB® Basic Functions Reference

MATLAB Environment		Defining and Changing Array Variables
<code>clc</code>	Clear command window	<code>a = 5</code> Define variable <code>a</code> with value 5
<code>help fun</code>	Display in-line help for <code>fun</code>	<code>A = [1 2 3; 4 5 6]</code> Define <code>A</code> as a 2x3 matrix “space” separates columns “;” or new line separates rows
<code>doc fun</code>	Open documentation for <code>fun</code>	<code>[A,B]</code> Concatenate arrays horizontally
<code>load("filename","vars")</code>	Load variables from .mat file	<code>[A;B]</code> Concatenate arrays vertically
<code>uiimport("filename")</code>	Open interactive import tool	<code>x(4) = 7</code> Change 4th element of <code>x</code> to 7
<code>save("filename","vars")</code>	Save variables to file	<code>A(1,3) = 5</code> Change <code>A(1,3)</code> to 5
<code>clear item</code>	Remove items from workspace	<code>x(5:10)</code> Get 5th to 10th elements of <code>x</code>
<code>examplescript</code>	Run the script file named <code>examplescript</code>	<code>x(1:2:end)</code> Get every 2nd element of <code>x</code> (1st to last)
<code>format style</code>	Set output display format	<code>x(x>6)</code> List elements greater than 6
<code>ver</code>	Get list of installed toolboxes	<code>x(x==10)=1</code> Change elements using condition
<code>tic, toc</code>	Start and stop timer	<code>A(4,:)</code> Get 4th row of <code>A</code>
<code>Ctrl+C</code>	Abort the current calculation	<code>A(:,3)</code> Get 3rd column of <code>A</code>
Operators and Special Characters		<code>A(6, 2:5)</code> Get 2nd to 5th element in 6th row of <code>A</code>
<code>+, -, *, /</code>	Matrix math operations	<code>A(:,[1 7])=A(:,[7 1])</code> Swap the 1st and 7th column
<code>.*, ./</code>	Array multiplication and division (element-wise operations)	<code>a:b</code> $[a, a+1, a+2, \dots, a+n]$ with $a+n \leq b$
<code>^, .^</code>	Matrix and array power	<code>a:ds:b</code> Create regularly spaced vector with spacing <code>ds</code>
<code>\</code>	Left division or linear optimization	<code>linspace(a,b,n)</code> Create vector of <code>n</code> equally spaced values
<code>., '</code>	Normal and complex conjugate transpose	<code>logspace(a,b,n)</code> Create vector of <code>n</code> logarithmically spaced values
<code>==, ~=, <, >, <=, >=</code>	Relational operators	<code>zeros(m,n)</code> Create <code>m x n</code> matrix of zeros
<code>&&, , ~, xor</code>	Logical operations (AND, NOT, OR, XOR)	<code>ones(m,n)</code> Create <code>m x n</code> matrix of ones
<code>;</code>	Suppress output display	<code>eye(n)</code> Create a <code>n x n</code> identity matrix
<code>...</code>	Connect lines (with break)	<code>A=diag(x)</code> Create diagonal matrix from vector
<code>% Description</code>	Comment	<code>x=diag(A)</code> Get diagonal elements of matrix
<code>'Hello'</code>	Definition of a character vector	<code>meshgrid(x,y)</code> Create 2D and 3D grids
<code>"This is a string"</code>	Definition of a string	<code>rand(m,n), randi</code> Create uniformly distributed random numbers or integers
<code>str1 + str2</code>	Append strings	<code>randn(m,n)</code> Create normally distributed random numbers
Special Variables and Constants		Complex Numbers
<code>ans</code>	Most recent answer	<code>i, j, li, lj</code> Imaginary unit
<code>pi</code>	$\pi=3.141592654\dots$	<code>real(z)</code> Real part of complex number
<code>i, j, li, lj</code>	Imaginary unit	<code>imag(z)</code> Imaginary part of complex number
<code>NaN, nan</code>	Not a number (i.e., division by zero)	<code>angle(z)</code> Phase angle in radians
<code>Inf, inf</code>	Infinity	<code>conj(z)</code> Element-wise complex conjugate
<code>eps</code>	Floating-point relative accuracy	<code>isreal(z)</code> Determine whether array is real

Elementary Functions

<code>sin(x), asin</code>	Sine and inverse (argument in radians)
<code>sind(x), asind</code>	Sine and inverse (argument in degrees)
<code>sinh(x), asinh</code>	Hyperbolic sine and inverse (arg. in radians)
Analogous for the other trigonometric functions: <code>cos, tan, csc, sec, and cot</code>	
<code>abs(x)</code>	Absolute value of x, complex magnitude
<code>exp(x)</code>	Exponential of x
<code>sqrt(x), nthroot(x,n)</code>	Square root, real nth root of real numbers
<code>log(x)</code>	Natural logarithm of x
<code>log2(x), log10</code>	Logarithm with base 2 and 10, respectively
<code>factorial(n)</code>	Factorial of n
<code>sign(x)</code>	Sign of x
<code>mod(x,d)</code>	Remainder after division (modulo)
<code>ceil(x), fix, floor</code>	Round toward +inf, 0, -inf
<code>round(x)</code>	Round to nearest decimal or integer

Tables

<code>table(var1,...,varN)</code>	Create table from data in variables var1, ..., varN
<code>readtable("file")</code>	Create table from file
<code>array2table(A)</code>	Convert numeric array to table
<code>T.var</code>	Extract data from variable var
<code>T(rows,columns), T(rows,["col1", "coln"])</code>	Create a new table with specified rows and columns from T
<code>T.varname=data</code>	Assign data to (new) column in T
<code>T.Properties</code>	Access properties of T
<code>categorical(A)</code>	Create a categorical array
<code>summary(T), groupsummary</code>	Print summary of table
<code>join(T1, T2)</code>	Join tables with common variables

Tasks (Live Editor)

Live Editor tasks are apps that can be added to a live script to interactively perform a specific set of operations. Tasks represent a series of MATLAB commands. To see the commands that the task runs, show the generated code.

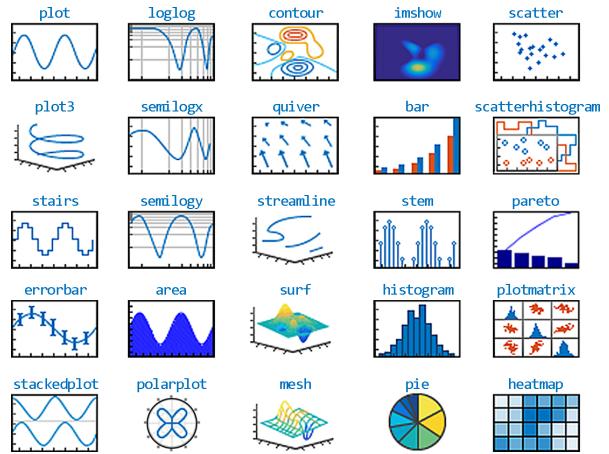
Common tasks available from the Live Editor tab on the desktop toolbar:

- Clean Missing Data
- Find Change Points
- Remove Trends
- Clean Outlier
- Find Local Extrema
- Smooth Data

Plotting

<code>plot(x,y,LineSpec)</code>	Plot y vs. x (<code>LineSpec</code> is optional) <code>LineSpec</code> is a combination of <code>linestyle</code> , <code>marker</code> , and <code>color</code> as a string. Example: <code>"-r"</code> = red solid line without markers
<code>title("Title")</code>	Add plot title
<code>legend("1st", "2nd")</code>	Add legend to axes
<code>x/y/zlabel("label")</code>	Add x/y/z axis label
<code>x/y/zticks(ticksvec)</code>	Get or set x/y/z axis ticks
<code>x/y/zticklabels(labels)</code>	Get or set x/y/z axis tick labels
<code>x/y/ztickangle(angle)</code>	Rotate x/y/z axis tick labels
<code>x/y/zlim</code>	Get or set x/y/z axis range
<code>axis(lim), axis style</code>	Set axis limits and style
<code>text(x,y,"txt")</code>	Add text
<code>grid on/off</code>	Show axis grid
<code>hold on/off</code>	Retain the current plot when adding new plots
<code>subplot(m,n,p), tiledlayout(m,n)</code>	Create axes in tiled positions
<code>yyaxis left/right</code>	Create second y-axis
<code>figure</code>	Create figure window
<code>gcf, gca</code>	Get current figure, get current axis
<code>clf</code>	Clear current figure
<code>close all</code>	Close open figures

Common Plot Types



Plot Gallery: mathworks.com/products/matlab/plot-gallery

Programming Methods

Functions

```
% Save your function in a function file or at the end
% of a script file. Function files must have the
% same name as the 1st function
function cavg = cumavg(x) %multiple args. possible
    cavg=cumsum(vec)./(1:length(vec));
end
```

Anonymous Functions

```
% defined via function handles
fun = @(x) cos(x.^2)./abs(3*x);
```

Control Structures

if, elseif Conditions

```
if n<10
    disp("n smaller 10")
elseif n<=20
    disp("n between 10 and 20")
else
    disp("n larger than 20")
```

Switch Case

```
n = input("Enter an integer: ");
switch n
    case -1
        disp("negative one")
    case {0,1,2,3} % check four cases together
        disp("integer between 0 and 3")
    otherwise
        disp("integer value outside interval [-1,3]")
end % control structures terminate with end
```

For-Loop

```
% loop a specific number of times, and keep
% track of each iteration with an incrementing
% index variable
for i = 1:3
    disp("cool");
end % control structures terminate with end
```

While-Loop

```
% loops as long as a condition remains true
n = 1;
nFactorial = 1;
while nFactorial < 1e100
    n = n + 1;
    nFactorial = nFactorial * n;
end % control structures terminate with end
```

Further programming/control commands

break	Terminate execution of for- or while-loop
continue	Pass control to the next iteration of a loop
try, catch	Execute statements and catch errors

Numerical Methods

fzero(fun,x0)	Root of nonlinear function
fminsearch(fun,x0)	Find minimum of function
fminbnd(fun,x1,x2)	Find minimum of fun in [x1, x2]
fft(x), ifft(x)	Fast Fourier transform and its inverse

Integration and Differentiation

integral(f,a,b)	Numerical integration (analogous functions for 2D and 3D)
trapz(x,y)	Trapezoidal numerical integration
diff(X)	Differences and approximate derivatives
gradient(X)	Numerical gradient
curl(X,Y,Z,U,V,W)	Curl and angular velocity
divergence(X,...,W)	Compute divergence of vector field
ode45(ode,tspan,y0)	Solve system of nonstiff ODEs
ode15s(ode,tspan,y0)	Solve system of stiff ODEs
deval(sol,x)	Evaluate solution of differential equation
pdepe(m,pde,ic,...bc,xm,ts)	Solve 1D partial differential equation
pdeval(m,xmesh,...usol,xq)	Interpolate numeric PDE solution

Interpolation and Polynomials

interp1(x,v,xq)	1D interpolation (analogous for 2D and 3D)
pchip(x,v,xq)	Piecewise cubic Hermite polynomial interpolation
spline(x,v,xq)	Cubic spline data interpolation
ppval(pp,xq)	Evaluate piecewise polynomial
mkpp(breaks,coeffs)	Make piecewise polynomial
unmkpp(pp)	Extract piecewise polynomial details
poly(x)	Polynomial with specified roots x
polyeig(A0,A1,...,Ap)	Eigenvalues for polynomial eigenvalue problem
polyfit(x,y,d)	Polynomial curve fitting
residue(b,a)	Partial fraction expansion/decomposition
roots(p)	Polynomial roots
polyval(p,x)	Evaluate poly p at points x
polyint(p,k)	Polynomial integration
polyder(p)	Polynomial differentiation



Accelerating the pace of engineering and science

Matrices and Arrays

<code>length(A)</code>	Length of largest array dimension
<code>size(A)</code>	Array dimensions
<code>numel(A)</code>	Number of elements in array
<code>sort(A)</code>	Sort array elements
<code>sortrows(A)</code>	Sort rows of array or table
<code>flip(A)</code>	Flip order of elements in array
<code>squeeze(A)</code>	Remove dimensions of length 1
<code>reshape(A,sz)</code>	Reshape array
<code>repmat(A,n)</code>	Repeat copies of array
<code>any(A), all</code>	Check if any/all elements are nonzero
<code>nnz(A)</code>	Number of nonzero array elements
<code>find(A)</code>	Indices and values of nonzero elements

Linear Algebra

<code>rank(A)</code>	Rank of matrix
<code>trace(A)</code>	Sum of diagonal elements of matrix
<code>det(A)</code>	Determinant of matrix
<code>poly(A)</code>	Characteristic polynomial of matrix
<code>eig(A), eigs</code>	Eigenvalues and vectors of matrix (subset)
<code>inv(A), pinv</code>	Inverse and pseudo inverse of matrix
<code>norm(x)</code>	Norm of vector or matrix
<code>expm(A), logm</code>	Matrix exponential and logarithm
<code>cross(A,B)</code>	Cross product
<code>dot(A,B)</code>	Dot product
<code>kron(A,B)</code>	Kronecker tensor product
<code>null(A)</code>	Null space of matrix
<code>orth(A)</code>	Orthonormal basis for matrix range
<code>tril(A), triu</code>	Lower and upper triangular part of matrix
<code>linsolve(A,B)</code>	Solve linear system of the form AX=B
<code>lsqminnorm(A,B)</code>	Least-squares solution to linear equation
<code>qr(A), lu, chol</code>	Matrix decompositions
<code>svd(A)</code>	Singular value decomposition
<code>gsvd(A,B)</code>	Generalized SVD
<code>rref(A)</code>	Reduced row echelon form of matrix

Descriptive Statistics

<code>sum(A), prod</code>	Sum or product (along columns)
<code>max(A), min, bounds</code>	Largest and smallest element
<code>mean(A), median, mode</code>	Statistical operations
<code>std(A), var</code>	Standard deviation and variance
<code>movsum(A,n), movprod, movmax, movmin, movmean, movmedian, movstd, movvar</code>	Moving statistical functions n = length of moving window
<code>cumsum(A), cumprod, cummax, cummin</code>	Cumulative statistical functions
<code>smoothdata(A)</code>	Smooth noisy data
<code>histcounts(X)</code>	Calculate histogram bin counts
<code>corrcoef(A), cov</code>	Correlation coefficients, covariance
<code>xcorr(x,y), xcov</code>	Cross-correlation, cross-covariance
<code>normalize(A)</code>	Normalize data
<code>detrend(x)</code>	Remove polynomial trend
<code>isoutlier(A)</code>	Find outliers in data

Symbolic Math*

<code>sym x, syms x y z</code>	Declare symbolic variable
<code>eqn = y == 2*a + b</code>	Define a symbolic equation
<code>solve(eqns,vars)</code>	Solve symbolic expression for variable
<code>subs(expr,var,val)</code>	Substitute variable in expression
<code>expand(expr)</code>	Expand symbolic expression
<code>factor(expr)</code>	Factorize symbolic expression
<code>simplify(expr)</code>	Simplify symbolic expression
<code>assume(var,assumption)</code>	Make assumption for variable
<code>assumptions(z)</code>	Show assumptions for symbolic object
<code>fplot(expr), fcontour, fsurf, fmesh, fimplicit</code>	Plotting functions for symbolic expressions
<code>diff(expr,var,n)</code>	Differentiate symbolic expression
<code>dsolve(deqn,cond)</code>	Solve differential equation symbolically
<code>int(expr,var,[a, b])</code>	Integrate symbolic expression
<code>taylor(fun,var,z0)</code>	Taylor expansion of function

*requires Symbolic Math Toolbox